

## Claims

What is claimed is:

1. A system for control signal generation using detected dynamic characteristics of frequency components of an incoming electronic signal, said incoming electronic signal comprising a fundamental frequency component and at least one overtone component of a higher frequency than said fundamental frequency component, said fundamental frequency component and said at least one overtone component comprising an amplitude parameter and a pitch parameter, said system comprising:
  - at least one bandpass filter adapted to isolate said at least one overtone component from said incoming electronic signal to produce an isolated overtone signal;
  - a separate signal parameter measurement element operatively coupled with each filter of said at least one bandpass filter, wherein said signal parameter measurement element provides amplitude measurement of said isolated overtone signal resulting in an isolated overtone parameter signal; and
  - a parameter signal processing unit for receiving said isolated overtone parameter signal, said parameter signal processing unit generating an outgoing control signal based upon said isolated overtone parameter signal.
2. The system according to claim 1, wherein said isolated overtone parameter signal comprises an amplitude parameter.
3. The system according to claim 1, wherein said signal parameter measurement element further provides pitch measurement resulting in said isolated overtone parameter signal comprising a pitch parameter.
4. The system according to claim 1, wherein said incoming electronic signal is generated by a vibration-sensing transducer in response to vibrations of a vibrating element

5. The system according to claim 1, wherein said incoming electronic signal  
2 further includes a plurality of overtone components, wherein each of said plurality of  
overtone components have a higher frequency than said fundamental frequency component,  
4 said fundamental frequency component and each of said plurality of overtone components  
comprising an amplitude parameter and a pitch parameter, said system further comprising:  
6 a filter bank comprising a plurality of said bandpass filters, wherein each bandpass  
filter of said plurality of bandpass filters is adapted to isolate a particular overtone component  
8 of said plurality of overtone components to generate an isolated overtone signal, said filter  
bank providing a plurality of isolated overtone signals generated by said plurality of bandpass  
10 filters, wherein;

12 said separate signal parameter measurement element is operatively coupled with each  
of said plurality of bandpass filters comprising said filter bank, wherein each of said plurality  
14 of signal parameter measurement elements is adapted to provide amplitude measurement of a  
particular isolated overtone signal of said plurality of isolated overtone signals to generate an  
isolated overtone parameter signal, and wherein;

16 said parameter signal processing unit is adapted to receive said isolated overtone  
parameter signal from each of said plurality of signal parameter measurement elements, said  
18 parameter signal processing unit generating at least one outgoing control signal based upon  
one or more of said plurality of isolated overtone parameter signals.

6. The system according to claim 1, wherein said incoming electronic signal is  
2 generated by a vibration-sensing transducer in response to a vibrating string.

7. The system according to claim 1, wherein said incoming electronic signal is  
2 generated by a vibration-sensing transducer in response to a human voice.

8. The system according to claim 7, wherein said human voice comprises at least  
2 one sung vowel.

9. The system according to claim 1, wherein said incoming electronic signal is  
2 generated by a vibration-sensing transducer in response to a vibrating reed.

10. The system according to claim 1, wherein said incoming electronic signal is  
2 generated by a vibration-sensing transducer in response to a vibrating column of air.

11. The system according to claim 1, wherein said incoming electronic signal is  
2 generated by a vibration-sensing transducer in response to a vibrating element of a  
percussion instrument.

12. The system according to claim 1, wherein said parameter processing unit  
2 generates said outgoing control signal based upon a ratio of a parameter of said isolated  
overtone parameter signal relative to a parameter of said fundamental frequency of said  
4 incoming electronic signal.

13. The system according to claim 5, wherein said parameter processing unit  
2 generates said outgoing control signal based upon a ratio of a first isolated overtone  
parameter signal associated with a first isolated overtone signal of said plurality of said  
4 isolated overtone signals relative to a second isolated overtone parameter signal associated  
with a second isolated overtone signal of said plurality of said isolated overtone signals.

14. The system according to claim 1, wherein said outgoing control signal  
2 comprises a signal of MIDI format.

15. The system according to claim 1, wherein said outgoing control signal  
2 comprises a signal of MIDI note format.

16. The system according to claim 1, wherein said outgoing control signal  
2 comprises a signal of MIDI continuous controller format.

17. The system according to claim 1, wherein said bandpass filter is a controllable  
2 bandpass filter.

18. The system according to claim 1, wherein said outgoing control signal is  
2 communicated to an external system comprising a synthesizer.

19. The system according to claim 1, wherein said outgoing control signal is  
2 communicated to an external system comprising a signal processor controlled by said  
outgoing control signal.

20. The system according to claim 1, wherein said incoming electronic signal is  
2 generated by a vibration-sensing transducer in response to plucking of a vibrating element.

21. The system according to claim 1, wherein said incoming electronic signal is  
2 generated by a vibration-sensing transducer in response to bowing of a vibrating element.

22. The system according to claim 1, wherein said incoming electronic signal is  
2 generated by a vibration-sensing transducer in response to vibrations of a vibrating element,  
wherein  
4 said incoming electronic signal is further amplified by an amplifier to produce an  
amplified drive signal, and wherein  
6 said amplified drive signal drives at least one drive transducer to stimulate said  
vibrating element.

23. The system according to claim 22, wherein said at least one drive transducer is  
2 a piezo transducer.

24. The system according to claim 22, wherein said vibration-sensing transducer  
2 is a piezo transducer.

25. The system according to claim 1, wherein variations of said isolated overtone  
2 parameter signal are tracked over time.

26. The system according to claim 1, wherein said isolated overtone parameter  
2 signal is further processed by nonlinear warping.

27. The system according to claim 1, wherein said signal parameter measurement  
2 element comprises a nonlinear warping characteristic.

28. The system according to claim 26, wherein said nonlinear warping is  
2 performed by said parameter processing unit.

29. The system according to claim 26, wherein said isolated overtone parameter  
2 signal comprises nonlinear warping exhibiting substantially logarithmic behavior.

30. The system according to claim 26, wherein said isolated overtone parameter  
2 signal comprises nonlinear warping exhibiting piecewise linear behavior.

31. The system according to claim 1, wherein said parameter processing unit  
2 generates said outgoing control signal by mathematical operations applied to a plurality of  
parameters of said isolated overtone parameter signal.

32. The system according to claim 31, wherein said mathematical operations  
2 include averaging a plurality of parameters of said isolated overtone parameter signal.

33. The system according to claim 31, wherein said mathematical operations  
2 include sums-of-squares calculations of a plurality of parameters of said isolated overtone  
parameter signal.

34. The system according to claim 5, wherein there is a plurality of said outgoing  
2 control signals, said plurality of said outgoing control signals communicated to an external  
synthesizer, wherein said external synthesizer generates a synthesized audio signal based  
4 upon and said outgoing control signal, wherein said synthesized audio signal complements a  
harmonic balance of said incoming electronic signal.

35. The system according to claim 5, wherein there is a plurality of said outgoing  
2 control signals, said plurality of said outgoing control signals communicated to an external  
synthesizer, where said external synthesizer generates a synthesized audio signal based upon  
4 said outgoing control signal, wherein said synthesized audio signal mimics a harmonic  
balance of said incoming electronic signal.

36. The system according to claim 1, wherein said parameter processing unit  
2 generates said outgoing control signal by assigning said isolated overtone parameter signal to  
a particular type of outgoing control signal.

37. The system according to claim 1, wherein said parameter processing unit  
2 combines a plurality of parameters of said isolated overtone parameter signal to generate a  
mathematically combined signal, and wherein said parameter processing unit generates said  
4 outgoing control signal by assigning said mathematically combined signal to a particular type  
of outgoing control signal.

38. The system according to claim 1, wherein said parameter processing unit  
2 processes a parameter of said isolated overtone parameter signal to generate a processed  
signal, and wherein said parameter processing unit generates said outgoing control signal by  
4 assigning said processed signal to a particular type of outgoing control signal.

39. The system according to claim 1, wherein said parameter processing unit  
2 processes a plurality of parameters of said isolated overtone parameter signal to generate a  
mathematically combined signal, and wherein said parameter processing unit generates said  
4 outgoing control signal by assigning said mathematically combined signal to a particular type  
of outgoing control signal.

40. The system according to claim 1, said system further comprising:  
2 a model-based overtone series calculator coupled with said bandpass filter, wherein  
said calculator provides filter control signals for centering said bandpass filter.

41. The system according to claim 40, wherein said calculator further provides  
2 overtone center line frequency information to one or more of said at least one bandpass  
filters.

42. A method for control signal generation using detected dynamic characteristics  
2 of frequency components of an incoming electronic signal, said incoming electronic signal  
comprising a fundamental frequency component and at least one overtone component of a  
4 higher frequency than said fundamental frequency component, said fundamental frequency  
component and said at least one overtone component comprising an amplitude parameter and  
6 a pitch parameter, said method comprising:

isolating said at least one overtone component from said incoming electronic signal  
8 using at least one bandpass filter, wherein said isolating results in the production of an  
isolated overtone signal;

10 measuring amplitude of said isolated overtone signal using a separate signal  
parameter measurement element operatively coupled with each filter of said at least one  
12 bandpass filter, wherein said measuring results in an isolated overtone parameter signal;

14 receiving said isolated overtone parameter signal at a parameter signal processing  
unit; and

16 generating an outgoing control signal at said parameter signal processing unit,  
wherein said outgoing control signal is generated based upon said isolated overtone  
parameter signal.

43. The method according to claim 42, wherein said isolated overtone parameter  
2 signal comprises an amplitude parameter.

44. The method according to claim 42, wherein said isolated overtone parameter  
2 signal comprises a pitch parameter.

45. The method according to claim 42, said method further comprising:  
2 generating said incoming electronic signal using a vibration-sensing transducer,  
wherein said incoming electronic signal is generated in response to vibrations present in a  
4 vibrating element.

46. The method according to claim 42, wherein said incoming electronic signal  
2 further includes a plurality of overtone components, wherein each of said plurality of  
overtone components have a higher frequency than said fundamental frequency component,  
4 said fundamental frequency component and each of said plurality of overtone components  
comprising an amplitude parameter and a pitch parameter, said method further comprising:  
6 isolating each overtone component of said plurality of overtone components of said  
incoming electronic signal using a corresponding plurality of bandpass filters, wherein said  
8 isolating of said plurality of overtone components generate a corresponding plurality of  
isolated overtone signals;  
10 directing each isolated overtone signal of said plurality of isolated overtone signals to  
a separate signal parameter measurement element;  
12 measuring amplitude of said plurality of isolated overtone signals to generate a  
corresponding plurality of isolated overtone parameter signals;  
14 receiving said plurality of isolated overtone parameter signals at a parameter signal  
processing unit; and  
16 generating at least one outgoing control signal for each parameter signal of said  
plurality of isolated overtone parameter signals.

47. The method according to claim 42, said method further comprising:  
2 generating said incoming electronic signal using a vibration-sensing transducer,  
wherein said incoming electronic signal is generated in response to vibration present in a  
4 vibrating string.

48. The method according to claim 42, said method further comprising:  
2 generating said incoming electronic signal using a vibration-sensing transducer,  
wherein said incoming electronic signal is generated in response to a human voice.

49. The method according to claim 48, wherein said human voice comprises at  
2 least one sung vowel.

50. The method according to claim 42, said method further comprising:  
2 generating said incoming electronic signal using a vibration-sensing transducer,  
wherein said incoming electronic signal is generated in response to a vibrating reed.

51. The method according to claim 42, said method further comprising:  
2 generating said incoming electronic signal using a vibration-sensing transducer,  
wherein said incoming electronic signal is generated in response to a vibrating column of air.

52. The method according to claim 42, said method further comprising:  
2 generating said incoming electronic signal using a vibration-sensing transducer,  
wherein said incoming electronic signal is generated in response to a vibrating element of a  
4 percussion instrument.

53. The method according to claim 42, wherein said parameter processing unit  
2 generates said outgoing control signal based upon a ratio of a parameter of said isolated  
overtone parameter signal relative to a parameter of said fundamental frequency of said  
4 incoming electronic signal.

54. The method according to claim 46, wherein said parameter processing unit  
2 generates said outgoing control signal based upon a ratio of a first isolated overtone  
parameter signal associated with a first isolated overtone signal of said plurality of said  
4 isolated overtone signals relative to a second isolated overtone parameter signal associated  
with a second isolated overtone signal of said plurality of said isolated overtone signals.

55. The method according to claim 42, wherein said outgoing control signal  
2 comprises a signal of MIDI format.

56. The method according to claim 42, wherein said outgoing control signal  
2 comprises a signal of MIDI note format.

57. The method according to claim 42, wherein said outgoing control signal  
2 comprises a signal of MIDI continuous controller format.

58. The method according to claim 42, wherein said bandpass filter is a  
2 controllable bandpass filter.

59. The method according to claim 42, wherein said outgoing control signal is  
2 communicated to an external system comprising a synthesizer.

60. The method according to claim 42, wherein said outgoing control signal is  
2 communicated to an external system comprising a signal processor controlled by said  
outgoing control signal.

61. The method according to claim 42, said method further comprising:  
2 generating said incoming electronic signal using a vibration-sensing transducer,  
wherein said incoming electronic signal is generated in response to plucking of said vibrating  
4 element.

62. The method according to claim 42, said method further comprising:  
2 generating said incoming electronic signal using a vibration-sensing transducer,  
wherein said incoming electronic signal is generated in response to bowing of said vibrating  
4 element.

63. The method according to claim 42, said method further comprising:  
2 generating said incoming electronic signal using a vibration-sensing transducer,  
wherein said incoming electronic signal is generated in response to vibration present in a  
4 vibrating element;

amplifying further said incoming electronic signal to produce an amplified drive  
6 signal; and

stimulating said vibrating element using at least one drive transducer driven by said  
8 amplified drive signal.

64. The method according to claim 63, wherein said at least one drive transducer  
2 is a piezo transducer.

65. The method according to claim 63, wherein said vibration-sensing transducer  
2 is a piezo transducer.

66. The method according to claim 42, wherein variations of said isolated  
2 overtone parameter signal are tracked over time.

67. The method according to claim 42, wherein said isolated overtone parameter  
2 signal is further processed by nonlinear warping.

68. The method according to claim 42, wherein said signal parameter  
2 measurement element comprises a nonlinear warping characteristic.

69. The method according to claim 67, wherein said nonlinear warping is  
2 performed by said parameter processing unit.

70. The method according to claim 67, wherein said isolated overtone parameter  
2 signal comprises nonlinear warping exhibiting substantially logarithmic behavior.

71. The method according to claim 67, wherein said isolated overtone parameter  
2 signal comprises nonlinear warping exhibiting piecewise linear behavior.

72. The method according to claim 42, wherein said parameter processing unit  
2 generates said outgoing control signal by mathematical operations applied to a plurality of  
parameters of said isolated overtone parameter signal.

73. The method according to claim 72, wherein said mathematical operations  
2 include averaging a plurality of parameters of said isolated overtone parameter signal.

74. The method according to claim 72, wherein said mathematical operations  
2 include sums-of-squares calculations of a plurality of parameters of said isolated overtone  
parameter signal.

75. The method according to claim 46, wherein there is a plurality of said  
2 outgoing control signals, said plurality of said outgoing control signals communicated to an  
external synthesizer, where said external synthesizer generates a synthesized audio signal  
4 based upon said outgoing control signal, wherein said synthesized audio signal complements  
a harmonic balance of said incoming electronic signal.

76. The method according to claim 73, wherein there is a plurality of said  
2 outgoing control signals, said plurality of said outgoing control signals communicated to an  
external synthesizer, where said external synthesizer generates a synthesized audio signal  
4 based upon said outgoing control signal, wherein said synthesized audio signal mimics a  
harmonic balance of said incoming electronic signal.

77. The method according to claim 42, wherein said parameter processing unit  
2 generates said outgoing control signal by assigning said isolated overtone parameter signal to  
a particular type of outgoing control signal.

78. The method according to claim 42, wherein said parameter processing unit  
2 combines a plurality of parameters of said isolated overtone parameter signal to generate a  
mathematically combined signal, and wherein said parameter processing unit generates said  
4 outgoing control signal by assigning said mathematically combined signal to a particular type  
of outgoing control signal.

79. The method according to claim 42, wherein said parameter processing unit  
2 processes a parameter of said isolated overtone parameter signal to generate a processed  
signal, and wherein said parameter processing unit generates said outgoing control signal by  
4 assigning said processed signal to a particular type of outgoing control signal.

80. The method according to claim 42, wherein said parameter processing unit  
2 processes a plurality of parameters of said isolated overtone parameter signal to generate a  
mathematically combined signal, and wherein said parameter processing unit generates said  
4 outgoing control signal by assigning said mathematically combined signal to a particular type  
of outgoing control signal.

81. The method according to claim 42, said method further comprising:  
2 coupling a model-based overtone series calculator with said bandpass filter, wherein  
said calculator provides filter control signals for centering said bandpass filter.

82. The method according to claim 81, wherein said calculator further provides  
2 overtone center line frequency information to one or more of said at least one bandpass filter.

83. A method for control signal generation using detected dynamic characteristics  
2 of frequency components of an incoming electronic signal, said incoming electronic signal  
comprising a fundamental frequency component and at least one overtone component of a  
4 higher frequency than said fundamental frequency component, said fundamental frequency  
component and said at least one overtone component comprising an amplitude parameter and  
6 a pitch parameter, said method comprising:

isolating said at least one overtone component from said incoming electronic signal to  
8 provide an isolated overtone signal;

measuring amplitude of said isolated overtone signal to generate an isolated overtone  
10 parameter signal comprising said amplitude; and

generating an outgoing control signal based upon said isolated overtone parameter  
12 signal, wherein said outgoing control signal is adapted to control an external system.

84. The method according to claim 83, wherein said isolated overtone parameter  
2 signal comprises an amplitude parameter.

85. The method according to claim 83, wherein said isolated overtone parameter  
2 signal comprises a pitch parameter.

86. The method according to claim 83, wherein said incoming electronic signal

2 further includes a plurality of overtone components, wherein each of said plurality of overtone components have a higher frequency than said fundamental frequency component, 4 said fundamental frequency component and each of said plurality of overtone components comprising an amplitude parameter and a pitch parameter, said method further comprising:

6 isolating each overtone component of said plurality of overtone components of said incoming electronic signal using a corresponding plurality of bandpass filters, wherein said 8 isolating of said plurality of overtone components generate a corresponding plurality of isolated overtone signals;

10 directing each isolated overtone signal of said plurality of isolated overtone signals to a separate signal parameter measurement element;

12 measuring amplitude of said plurality of isolated overtone signals to generate a corresponding plurality of isolated overtone parameter signals;

14 receiving said plurality of isolated overtone parameter signals at a parameter signal processing unit; and

16 generating a separate outgoing control signal for each parameter signal of said plurality of isolated overtone parameter signals.

87. The method according to claim 83, wherein said parameter processing unit

2 generates said outgoing control signal based upon a ratio of a parameter of said isolated overtone parameter signal relative to a parameter of said fundamental frequency of said 4 incoming electronic signal.

88. The method according to claim 83, wherein said parameter processing unit

2 generates said outgoing control signal based upon a ratio of a first parameter of said isolated overtone parameter signal relative to a second parameter of said isolated overtone parameter 4 signal.

89. The method according to claim 83, wherein said outgoing control signal

2 comprises a signal of MIDI format.

90. The method according to claim 83, wherein said outgoing control signal is  
2 communicated to an external system comprising a synthesizer.

91. The method according to claim 83, wherein said outgoing control signal is  
2 communicated to an external system comprising a signal processor controlled by said  
outgoing control signal.

92. The method according to claim 83, wherein variations of said isolated  
2 overtone parameter signal are tracked over time.

93. The method according to claim 83, wherein said isolated overtone parameter  
2 signal is further processed by nonlinear warping.

94. The method according to claim 83, wherein said parameter processing unit  
2 generates said outgoing control signal by mathematical operations applied to a plurality of  
parameters of said isolated overtone parameter signal.

95. The method according to claim 83, said method further comprising:  
2 coupling a model-based overtone series calculator with said bandpass filter, wherein  
said calculator provides filter control signals for centering said bandpass filter.

96. The method according to claim 95, wherein said calculator further provides  
2 overtone center line frequency information to one or more of said at least one bandpass filter.